

# Charon-Suite Module Framework

## Modular Algorithms with Serializable C++ Objects

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# Outline

## 1 Charon-Suite

- Serializable Objects
- Workflows

## 2 Helper Tools

- Tuchulcha
- Template-Generator
- Examples and Documentation
- Precompiled Binaries

## 3 Application

- Optical Flow Estimation
- 3D Reconstruction
- Parallel Calculations

# Project Overview

What is Charon-Suite? Why was it created?

- image processing libraries difficult to maintain and extend in a research environment, steep learning curve, short life-cycle
- Charon-Suite is a framework with associated tools rather than a library

## Charon-Suite

- open source framework for computer vision prototyping
- independent of any given image processing library
- simple plugin-architecture for parts of computer vision algorithms
- modules may use any language and any software package
- graphical helper tools for configuration and execution
- easy to learn, cross-platform

# Used Software

Dependencies and Build Tools, License Information



## framework

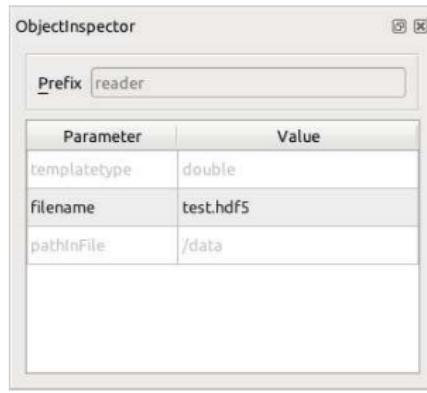
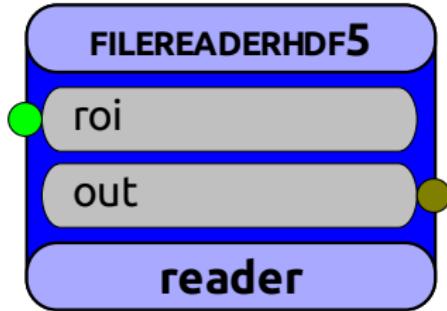
- framework written in C++
- build using cmake
- documentation with doxygen
- GUI elements using Qt4
- core and helper classes under GNU GPLv3
- platform independent; supported: Win32/64 with MsVC, Linux/GCC, Mac/GCC

## modules

- arbitrary libraries may be used: CImg, Vigras, Qt, Petsc, OpenCV and more
- wrapper modules for other languages; already available: python, matlab, scripts
- most modules also use LGPL, but other licenses possible

# Charon Modules

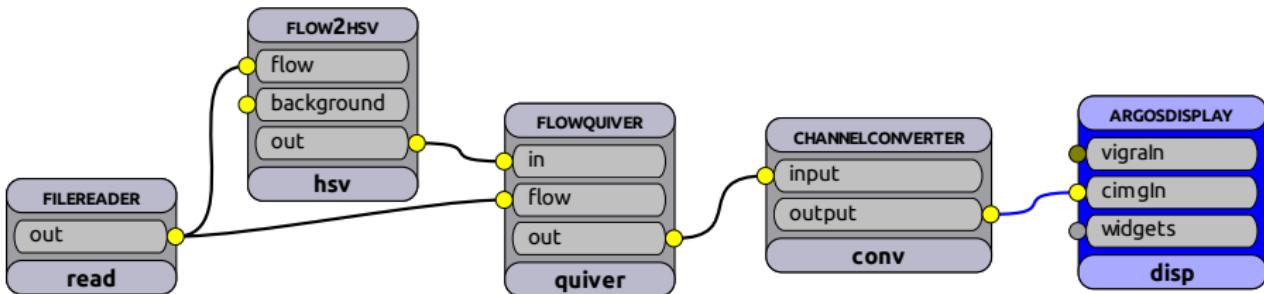
Dividing Algorithms into Parts using Serializable Objects



- algorithmic steps divided into different modules (e.g. read data, processing steps, write result)
- modules encapsulate algorithm parameters and their documentation
- load/store parameters from/to parameter files (plain text)
- white-box testing of parts and full algorithms possible
- re-usability of existing modules without introducing new bugs

# Module Interaction

## Data Flow/Slot Model



- slot mechanism for data exchange between modules
- full algorithm described by interaction of modules
- directed acyclic graph required
- save connections also in the plain text parameter file
- flow chart visualization
- execution by traversing the modules of this graph

# Tool Overview

## Simplify Usage and Development

### main tools

`templategenerator` set up code templates for new modules

`tuchulcha` graphical workflow configuration and execution tool

`paraminspector` parameter file editor, standalone object inspector

### tools for scripting

`workflow-executor` command line workflow executor

`charon-xml-helper` check module groups in doxygen documentation

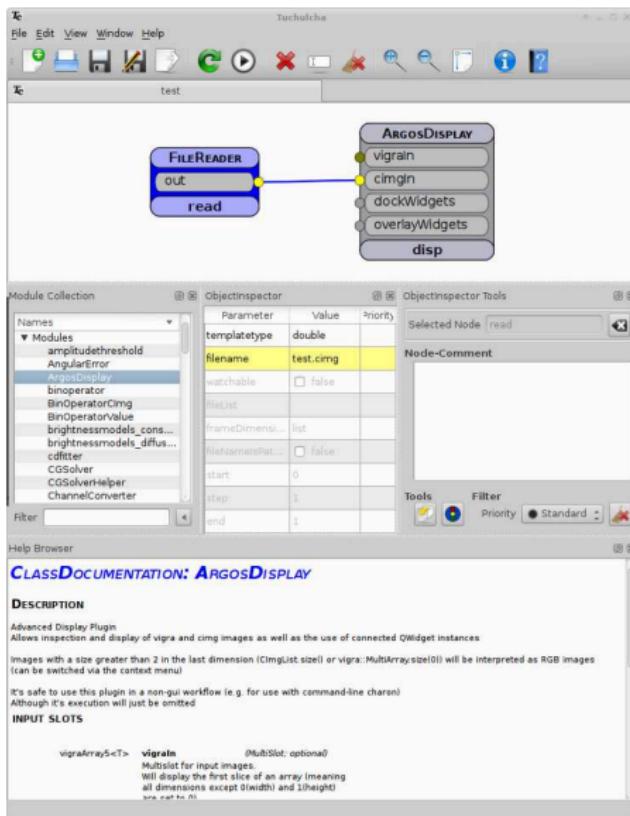
### web-based services

`sourceforge` code hosting, wiki, tutorials, project web, win releases

`launchpad` code hosting, ubuntu package repository, recipe-builds

# Tuchulcha

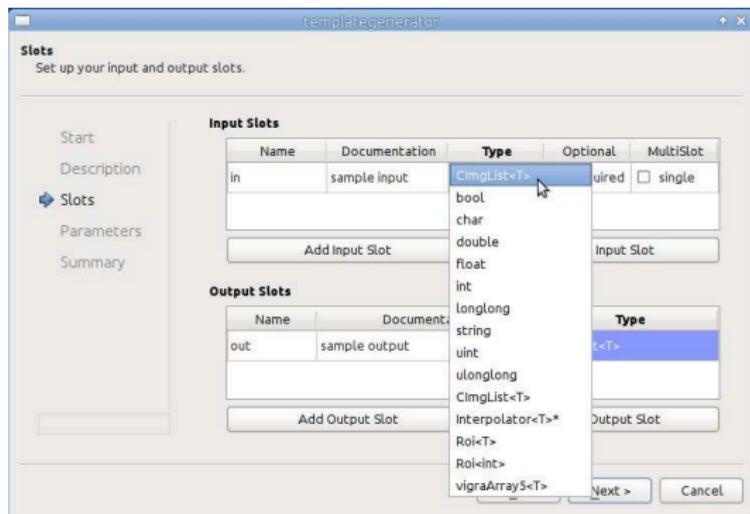
## Graphical Workflow Configuration



- overview of available modules
- module documentation
- graphical workflow and connection management (like LabView or similar)
- parameter adjustment using the object inspector
- workflow execution
- qt event loop for display modules
- node/workflow comments
- parameter priorities

# Template Generator

## Code Templates for New Modules



- wizard simplify generating new modules
- specification of class name, input/output slots and parameters with their types and documentation
- generation of C++ files `module.h` `module.hxx` `module.cpp` and CMake `CMakeLists.txt`
- placeholder to add execution code

# Examples and Documentation

Information at the Sourceforge Project Page

The project page at sourceforge is the place to start working with the Charon-Suite framework. There is information for beginners as well as for experienced users.

- project wiki with tutorials, build instructions and links to other information sources  
<http://charon-suite.sf.net>
- doxygen documentation  
<http://charon-suite.sf.net/doc/project>
- tool references, usage and options (manpages)  
<http://charon-suite.sf.net/doc/man>
- example workflows with detailed description and needed data  
<http://charon-suite.sf.net/doc/examples>

# Testing

## Test Suite and Dashboard Overview

### Charon-Suite Testing

- test suite for base classes and module collections
- automated tests based on CTest
- continuous and nightly tests (using scripts)
- automated documentation, examples and manpage generation
- test result overview using CDash dashboard  
<http://charon-suite.sf.net/CDash/>



# Precompiled Binaries

Using Charon-Suite without compiling anything

- get Charon-Suite running in a few minutes only
- download and unpack, run tuchulcha
- use example workflows with demo algorithms
- adapt these workflows to your needs

## available binaries

- Win32/Win64 MsVC 2010
- Ubuntu Linux DEB Packages Repository with all dependencies
- Gentoo Linux Ebuilds (layman overlay)

<http://sf.net/apps/trac/charon-suite/wiki/InstallationGuide>

# Module Collections

## Overview of Existing Modules

`charon-utils` data input/output, image manipulation

`charon-flow` optical flow estimation and related modules

`hekate` 3D reconstruction and related modules

`charon-petsc` parallel calculations using MPI

### *charon-utils:* supported data formats

- cimg, pgm, bmp
- jpeg, tiff, png via external libraries
- all formats supported by ImageMagic
- hdf5 via vigra library

# Charon-Flow

## Various Optical Flow Estimation Algorithms

### working algorithms

- Horn and Schunck (1981)
- Lukas and Kanade (1981)
- combined local/global  
(Bruhn et al. 2005)
- nonlinear and multiscale versions  
(Pyramids)
- learning flow (Sun et al. 2008)
- Charbonnier functions  
(Charbonnier et al. 1997)  
(Papenberg et al. 2006)
- Classic+NL (Sun et al. 2010)
- Range-Flow (Scene-Flow)

### helpers

- CImgList based iterators  
(loops in workflows)
- contrastive divergence (CD)  
learning algorithm  
(Hinton 2002)
- monte carlo sampling  
(Metropolis et al. 1953)
- PDE solvers based on Petsc,  
conjugate gradients, SOR,  
Cuda Version (approx.),  
2nd Order Newton

# Hekate

## Camera Calibration, Feature Detection and 3D Reconstruction

### Algorithms

- 3D Reconstruction by Structure from Motion (SfM)<sup>12</sup>
- Feature Detection and Tracking (for example SIFT features)
- Outlier elimination of feature correspondences<sup>23</sup>
- Delaunay triangulation to generate meshes
- Auto-calibration of cameras by image sequence
- Results can be used for camera tracking

### References

- ① G.Wang and J.Wu. *Guide to 3D Structure and Motion Estimation*, 2011
- ② R. Hartley and A. Zisserman. *Multiple View Geometry in Computer Vision*, 2004
- ③ L. Xiangru and H. Zhanyi. *Rejecting Mismatches by Correspondence Function*, 2010

For more information ask Moritz Becker

# Charon-Petsc

## MPI-Based Workflows

### features

- multi processing using `mpirun`
- wrapping parallel vector and sparse matrix classes
- export to matlab vectors
- operations like add and multiply with matrices and vectors
- parallel filtering (derivation, convolution with gaussian)
- converters from and to existing image types (VigraMultiArray)

### work-in-progress

- wrapping KSP solver class
- mixing parallel and non-parallel modules

For more information ask  
Gerald Mwangi

# Conclusion

## summary

- open source framework
- modular architecture
- stable since 2009
- increasing number of available algorithms
- precompiled binaries for fast setup
- no need to reinvent the wheel
- application not restricted to computer vision

## thanks to

- Daniel Kondermann (project initiator)
- Stephan Meister (charon-utils, argos)
- Michael Baron (charon-flow)
- Moritz Becker (hekate)
- Gerald Mwangi (charon-petsc)